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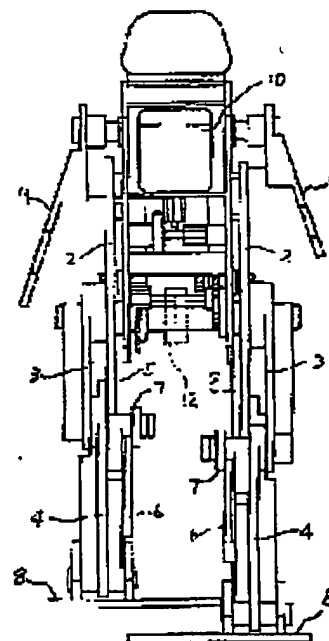
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(54) ROBOT TOY

(57)Abstract:

PROBLEM TO BE SOLVED: To provide a bipedalism robot toy hard to fall down even if it walks with long steps.

SOLUTION: This robot toy is provided with walking mechanisms 1 to 8 adapted to walk by repeatedly letting out one leg in front of or in the rear of the other leg and stopping means 12, 31, 32, 33 for stopping walking in a fixed walking attitude. Thus, stopping in the state of being easy to fall is avoided in walking with long steps.



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